

# Outerspace

Reactive robotic creature

A project by Andre Stubbe and Markus Lerner

<http://www.outerspace-robot.com>

## Technical rider

### 1. Robot

**Size of base**

40 x 40 x 15 cm (L\*B\*H)

**Length of arm**

about 55 cm

**Weight**

7,5 kg

**Connections**

90–240 V power adaptor with europlug (Type C European 2-pin)

**Time for setup**

about 30 mins

**Time for breakdown**

about 15 mins

### 2. Transport Box

**Type**

Aluminium box with 2 handles for horizontal transport and 1 handle for vertical transport

**Size**

45 x 55 x 35 cm (L\*W\*H)

**Weight**

15 kg (including robot)

### 3. Setup requirements

1. A white pedestal measuring 60 x 60 x 75 cm (LxWxH) is the perfect stand for the robot.
2. Ideally a hole is placed centrally under the robot. The small plug of the power cable has to fit through this hole. In this way the power supply of the robot is invisible and nobody can get their hands on it.
3. A light spot exactly above Outerspace is ideal, too. Outerspace needs light, it can't see well in the dark.